

We need to solve the coupled equations:

$$i \dot{a}_0 = \omega_0 a_0 + \lambda \sqrt{\frac{\Delta\omega}{\hbar}} \sum_{n=1}^{2N-1} a_n \quad \text{and} \quad i \dot{a}_n = \omega_n a_n + \lambda \sqrt{\frac{\Delta\omega}{\hbar}} a_0$$

Formally these equations can be written as

$$\frac{d}{dt} \vec{a} = -i \underline{M} \vec{a}$$

From the 10th page of Chap 7 notes, $\Gamma = \frac{2\pi\lambda^2}{\hbar} \Rightarrow \lambda \sqrt{\frac{\Delta\omega}{\hbar}} = \sqrt{\frac{\Delta\omega}{2\pi}} \Gamma$
and $\omega_n = \omega_0 + (n-N)\Delta\omega$

The matrix has the form with $\zeta = \sqrt{\Gamma\Delta\omega/2\pi}$

$$\underline{M} = \begin{pmatrix} \omega_0 & \zeta & \zeta & \zeta & \dots \\ \zeta & \omega_1 & & & \\ \zeta & & \omega_2 & & \\ \vdots & & & \ddots & \end{pmatrix}$$

A method for numerically solving these equations is the Leap Frog algorithm

$$\frac{d\vec{a}(t)}{dt} = \frac{\vec{a}(t+\delta t) - \vec{a}(t-\delta t)}{2\delta t} = -i \underline{M} \vec{a}(t)$$

The left hand side is $O(\delta t^2)$ accurate. More importantly one can show that this approximation conserves the norm of \vec{a} if \underline{M} is hermitian.

One can implement this in the following way

$$\vec{a}(2\delta t) = \vec{a}(0) - 2i\delta t \underline{M} \vec{a}(\delta t)$$

$$\vec{a}(3\delta t) = \vec{a}(\delta t) - 2i\delta t \underline{M} \vec{a}(2\delta t)$$

etc

Note that even time steps use the odd steps and vice versa

$$\vec{a}_e = \vec{a}_e - 2i\delta t \underline{M} \vec{a}_o$$

$$\vec{a}_e = \vec{a}(2\delta t)$$

$$\vec{a}_o = \vec{a}_o - 2i\delta t \underline{M} \vec{a}_e$$

$$\vec{a}_o = \vec{a}(3\delta t)$$

etc

Given $\vec{a}(0)$ how to get $\vec{a}(\delta t)$? Since \underline{M} is independent of time

$$\vec{a}(\delta t) = \exp[-i\delta t \underline{M}] \vec{a}(0) = \vec{a}(0) - i\delta t \underline{M} \vec{a}(0) - \frac{\delta t^2}{2} \underline{M} \underline{M} \vec{a}(0) \dots$$

The evaluation of this series without the use of another complex vector is somewhat tricky. Since we only need $\vec{a}(\delta t)$ through $O(\delta t^2)$, this can be accomplished through the steps:

$$\begin{aligned}\vec{a}(\delta t) &= \left(1 - i\mu\delta t - \frac{\delta t^2}{2}\mu\mu\right)\vec{a}(0) \\ &= \vec{a}(0) - i\mu\delta t \left(1 - i\frac{\delta t}{2}\mu\right)\vec{a}(0)\end{aligned}$$

The following nonintuitive algorithm accomplishes these steps

$$\vec{a}_0 = \vec{a}(0)$$

$$\vec{a}_e = \vec{a}_0 - i\frac{\delta t}{2}\mu\vec{a}_0$$

$$\vec{a}_o = \vec{a}_0 - i\delta t\mu\vec{a}_e$$

$$\vec{a}_e = \vec{a}(0)$$

At this point $\vec{a}_e = \vec{a}(0)$ and $\vec{a}_o = \vec{a}(\delta t) + \text{errors } O(\delta t^3)$